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**STABILITY OF SOLUTIONS OF INFINITE SYSTEMS  
OF NONLINEAR DIFFERENTIAL-FUNCTIONAL  
EQUATIONS OF PARABOLIC TYPE**

**Abstract.** A parabolic initial boundary value problem and an associated elliptic Dirichlet problem for an infinite weakly coupled system of semilinear differential-functional equations are considered. It is shown that the solutions of the parabolic problem is asymptotically stable and the limit of the solution of the parabolic problem as  $t \rightarrow \infty$  is the solution of the associated elliptic problem. The result is based on the monotone methods.

**Keywords:** stability of solutions, infinite systems, parabolic equations, elliptic equations, semilinear differential-functional equations, monotone iterative method.

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Let  $S$  be an infinite set. Let  $G \subset \mathbb{R}^m$  be an open bounded domain with  $C^{2+\alpha}$  boundary ( $\alpha \in (0, 1)$ ) and  $D := (0, T) \times G$ , where  $T \leq \infty$ . Let  $\bar{D} := [0, T) \times \bar{G}$ .

We consider a boundary initial value problem for an infinite weakly coupled system of semilinear autonomous differential-functional parabolic equations of the form:

$$\frac{\partial u^i(t, x)}{\partial t} - \mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) \quad \text{for } t > 0, x \in G, i \in S, \quad (1)$$

$$u^i(t, x) = h^i(x) \quad \text{for } t > 0, x \in \partial G, i \in S, \quad (2)$$

$$u^i(0, x) = h^i(x) \quad \text{for } x \in \bar{G}, i \in S \quad (3)$$

and the associated Dirichlet problem for an infinite weakly coupled system of semilinear differential-functional elliptic equations of the form:

$$-\mathcal{L}^i[u^i](x) = f^i(x, u(x), u(\cdot)) \quad \text{for } x \in G, i \in S, \quad (4)$$

$$u^i(x) = h^i(x) \quad \text{for } x \in \partial G, \quad i \in S, \quad (5)$$

where

$$\mathcal{L}^i[u^i](t, x) := \sum_{j,k=1}^m a_{jk}^i(x) u_{x_j x_k}^i(t, x) + \sum_{j=1}^m b_j^i(x) u_{x_j}^i(t, x)$$

are strongly uniformly elliptic in  $\bar{G}$ ,

$$f^i: \bar{G} \times \mathcal{B}(S) \times C_S(\bar{G}) \ni (x, y, z) \mapsto f^i(x, y, z) \in \mathbb{R}$$

for every  $i \in S$ . The notation  $f(x, u(x), u(\cdot))$  means that the dependence of  $f$  on the second variable is a function-type dependence and on the third variable is a functional-type dependence. In (1),  $f(x, u(t, x), u(t, \cdot))$  means that the dependence on the third variable is a functional-type dependence with respect to  $x$ , but a function-type dependence with respect to  $t$ .

The following results extend and generalize the results of D.H. Sattinger [7], H. Amann [3] and S. Brzychczy [4].

We use the following notation. Let  $\mathcal{B}(S)$  be the Banach space of all bounded functions  $w: S \rightarrow \mathbb{R}$ ,  $w(i) = w^i$  ( $i \in S$ ) with the norm  $\|w\|_{\mathcal{B}(S)} := \sup_{i \in S} |w^i|$ .  $\mathcal{B}(S)$  is endowed with a partial order  $w \leq \tilde{w}$  defined as  $w^i \leq \tilde{w}^i$  for every  $i \in S$ . Elements of  $\mathcal{B}(S)$  will be denoted by  $(w^i)_{i \in S}$ , too. Let  $C(\bar{G})$  be the space of all continuous functions  $v: \bar{G} \rightarrow \mathbb{R}$  with the norm  $\|v\|_{C(\bar{G})} := \max_{x \in \bar{G}} |v(x)|$ . In this space,  $v \leq \tilde{v}$  means that  $v(x) \leq \tilde{v}(x)$  for every  $x \in \bar{G}$ . By  $C^{l+\alpha}(\bar{G})$ , where  $l = 0, 1, 2, \dots$  and  $\alpha \in (0, 1)$ , we denote the space of all functions continuous in  $\bar{G}$  with derivatives of order less or equal  $l$  being Hölder continuous with exponent  $\alpha$  in  $G$  (see [6, pp. 52–53]) and by  $C^{l+\alpha}(\bar{D})$ , where  $l = 0, 1, 2, \dots$  and  $\alpha \in (0, 1)$ , we denote the space of all functions continuous in  $\bar{D}$  with all derivatives  $\frac{\partial^{r+s}}{\partial t^r \partial x^s}$  being Hölder continuous with exponent  $\alpha$  in  $D$  if  $0 \leq 2r + s \leq l$  (see [5, pp. 37–38]). By  $H^{l,p}(G)$  we denote the Sobolev space of all functions whose weak derivatives of order  $l$  are in  $L^p(G)$  (see [1, pp. 44–46]). A notation  $g \in C^{l+\alpha}(\partial G)$  (resp.  $g \in H^{l,p}(\partial G)$ ) means that there exists a function  $\mathbf{g} \in C^{l+\alpha}(\bar{G})$  (resp.  $\mathbf{g} \in H^{l,p}(G) \cap C(\bar{G})$ ) such that  $\mathbf{g}(x) = g(x)$  for every  $x \in \partial G$ . In these spaces, norms are defined as  $\|g\|_{C^{l+\alpha}(\partial G)} := \inf_{\mathbf{g} \in C^{l+\alpha}(\bar{G}): \forall x \in \partial G: \mathbf{g}(x) = g(x)} \|\mathbf{g}\|_{C^{l+\alpha}(\bar{G})}$  and  $\|g\|_{H^{2,p}(\partial G)} := \inf_{\mathbf{g} \in H^{2,p}(G) \cap C(\bar{G}): \forall x \in \partial G: \mathbf{g}(x) = g(x)} \|\mathbf{g}\|_{H^{2,p}(G)}$ , respectively.

We denote  $z = (z^i)_{i \in S} \in C_S(\bar{G})$  if  $z: \bar{G} \rightarrow \mathcal{B}(S)$  and  $z^i: \bar{G} \rightarrow \mathbb{R}$  ( $i \in S$ ) is a continuous function with  $\sup_{i \in S} \|z^i(x)\|_{C(\bar{G})} < \infty$ . The space  $C_S(\bar{G})$  is a Banach space with the norm  $\|z\|_{C_S(\bar{G})} := \sup_{i \in S} \|z^i(x)\|_{C(\bar{G})}$  and the partial order  $z \leq \tilde{z}$  defined as  $z^i(x) \leq \tilde{z}^i(x)$  for every  $x \in \bar{G}$ ,  $i \in S$ . The space  $C_S^{l+\alpha}(\bar{G})$  is the space of all functions  $(z^i)_{i \in S}$  such that  $z^i \in C^{l+\alpha}(\bar{G})$  for every  $i \in S$  and  $\sup_{i \in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{G})} < \infty$ . In this space, the norm is defined as  $\|z(x)\|_{C_S^{l+\alpha}(\bar{G})} = \sup_{i \in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{G})}$ . In similar way,  $C_S^{l+\alpha}(\bar{D})$  is the space of all functions  $(z^i)_{i \in S}$  such that  $z^i \in C^{l+\alpha}(\bar{D})$  for every  $i \in S$  and  $\sup_{i \in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{D})} < \infty$  with the norm  $\|z(x)\|_{C_S^{l+\alpha}(\bar{D})} = \sup_{i \in S} \|z^i(x)\|_{C^{l+\alpha}(\bar{D})}$ . We will write that  $z = (z^i)_{i \in S} \in L_S^p(G)$  if  $z^i \in L^p(G)$  for every  $i \in S$  and

$\sup_{i \in S} \|z^i(x)\|_{L^p(G)} < \infty$ . A notation  $z = (z^i)_{i \in S} \in H_S^{l,p}(G)$  means that  $z^i \in H^{l,p}(G)$  for every  $i \in S$  and  $\sup_{i \in S} \|z^i(x)\|_{H^{l,p}(G)} < \infty$ . In these spaces, norms are defined as  $\|z(x)\|_{L_S^p(G)} = \sup_{i \in S} \|z^i(x)\|_{L^p(G)}$  and  $\|z(x)\|_{H_S^{l,p}(G)} = \sup_{i \in S} \|z^i(x)\|_{H^{l,p}(G)}$ , respectively.

A function  $\tilde{u}$  is said to be *regular in  $\bar{D}$*  if  $\tilde{u} \in C_S(\bar{D})$  and  $\tilde{u}$  has continuous derivatives  $\frac{\partial \tilde{u}}{\partial t}$ ,  $\frac{\partial \tilde{u}}{\partial x_j}$ ,  $\frac{\partial^2 \tilde{u}}{\partial x_j \partial x_k}$  in  $D$  for  $j, k = 1..m$ . A function  $\tilde{u}$  is said to be a *classical (regular) solution* of problem (1), (2), (3) in  $\bar{D}$  if  $\tilde{u}$  is regular in  $\bar{D}$  and fulfils the system of equations (1) in  $D$  with conditions (2) and (3). A function  $\tilde{u}$  is said to be a *weak solution* of problem (1), (2), (3) in  $\bar{D}$  if  $\tilde{u}(t, \cdot) \in L_S^2(G)$ ,  $\frac{\partial \tilde{u}^i(t, \cdot)}{\partial t} \in L^2(G)$ ,  $\mathcal{L}^i[\tilde{u}^i](t, \cdot) \in L^2(G)$  and

$$\left\langle \frac{\partial \tilde{u}^i(t, x)}{\partial t}, \xi(x) \right\rangle - \langle \mathcal{L}^i[\tilde{u}^i](t, x), \xi(x) \rangle = \langle f^i(x, \tilde{u}(t, x), \tilde{u}(t, \cdot)), \xi(x) \rangle$$

for every  $t > 0$ ,  $i \in S$  and for any test function  $\xi \in C_0^\infty(\bar{G})$ , where  $\langle \cdot, \cdot \rangle$  is the inner product in  $L^2(G)$ , i.e.,  $\langle f, g \rangle = \int_G fg \, dx$  and  $\tilde{u}$  fulfils conditions (2), (3) in trace sense.

A function  $\hat{u}$  is said to be *regular in  $\bar{G}$*  if  $\hat{u} \in C_S(\bar{G}) \cap C_S^2(G)$ . A function  $\hat{u}$  is said to be a *classical (regular) solution* of problem (4), (5) in  $\bar{G}$  if  $\hat{u}$  is regular in  $\bar{G}$  and fulfils the system of equations (4) in  $G$  with condition (5). A function  $\hat{u}$  is said to be a *weak solution* of problem (4), (5) in  $\bar{G}$  if  $\hat{u} \in L_S^2(G)$ ,  $\mathcal{L}^i[\hat{u}^i] \in L^2(G)$  and

$$-\langle \mathcal{L}^i[\hat{u}^i](x), \xi(x) \rangle = \langle f^i(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \rangle$$

for every  $i \in S$  and for any test function  $\xi \in C_0^\infty(\bar{G})$  and  $\hat{u}$  fulfils condition (5) in trace sense.

A solution  $\hat{u}(x)$  of elliptic problem (4), (5) is said to be a *stable solution of parabolic problem (1), (2), (3)* if for any  $\epsilon > 0$  there exists a  $\delta > 0$  such that  $\|\hat{u}(\cdot) - h(\cdot)\|_{C_S(\bar{G})} < \delta$  implies  $\|\hat{u}(\cdot) - \tilde{u}(t, \cdot)\|_{C_S(\bar{G})} < \epsilon$  for each  $t > 0$ , where  $\tilde{u}(t, x)$  is a solution of parabolic problem (1), (2), (3). A solution  $\hat{u}(x)$  is called an *asymptotically stable solution of parabolic problem (1), (2), (3)* if it is a stable solution of parabolic problem (1), (2), (3) and  $\lim_{t \rightarrow \infty} \|\hat{u}(\cdot) - \tilde{u}(t, \cdot)\|_{C_S(\bar{G})} = 0$ .

Functions  $\tilde{u}_0 = \tilde{u}_0(t, x)$  and  $\tilde{v}_0 = \tilde{v}_0(t, x)$  regular in  $\bar{D}$ , satisfying the infinite systems of inequalities

$$\begin{cases} \frac{\partial \tilde{u}_0^i(t, x)}{\partial t} - \mathcal{L}^i[\tilde{u}_0^i](t, x) \leq f^i(x, \tilde{u}_0(t, x), \tilde{u}_0(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ \tilde{u}_0^i(t, x) \leq h^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ \tilde{u}_0^i(0, x) \leq h^i(x) & \text{for } x \in \bar{G}, i \in S \end{cases} \quad (6)$$

$$\begin{cases} \frac{\partial \tilde{v}_0^i(t, x)}{\partial t} - \mathcal{L}^i[\tilde{v}_0^i](t, x) \geq f^i(x, \tilde{v}_0(t, x), \tilde{v}_0(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ \tilde{v}_0^i(t, x) \geq h^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ \tilde{v}_0^i(0, x) \geq h^i(x) & \text{for } x \in \bar{G}, i \in S \end{cases} \quad (7)$$

are called a *lower* and an *upper function*, respectively, for parabolic problem (1), (2), (3) in  $\bar{D}$ . In a similar way, functions  $\hat{u}_0 = \hat{u}_0(x)$  and  $\hat{v}_0 = \hat{v}_0(x)$  regular in  $\bar{G}$ , satisfying the infinite systems of inequalities

$$\begin{cases} -\mathcal{L}^i[\hat{u}_0^i](x) \leq f^i(x, \hat{u}_0(x), \hat{u}_0(\cdot)) & \text{for } x \in G, i \in S, \\ \hat{u}_0^i(x) \leq h^i(x) & \text{for } x \in \partial G, i \in S, \end{cases} \tag{8}$$

$$\begin{cases} -\mathcal{L}^i[\hat{v}_0^i](x) \geq f^i(x, \hat{v}_0(x), \hat{v}_0(\cdot)) & \text{for } x \in G, i \in S, \\ \hat{v}_0^i(x) \geq h^i(x) & \text{for } x \in \partial G, i \in S \end{cases} \tag{9}$$

are called a *lower* and an *upper function*, respectively, for elliptic problem (4), (5) in  $\bar{G}$ .

We define

$$\mathcal{K} := \{(x, y, z) : x \in \bar{G}, y \in [m_0, M_0], z \in \langle u_0, v_0 \rangle\},$$

where  $m_0 := (m_0^i)_{i \in S}$ ,  $M_0 := (M_0^i)_{i \in S}$ ,  $m_0^i := \min_{x \in \bar{G}} u_0^i(x)$ ,  $M_0^i := \max_{x \in \bar{G}} v_0^i(x)$  and  $\langle u_0, v_0 \rangle := \{\zeta \in L_S^p(G) : u_0(x) \leq \zeta(x) \leq v_0(x) \text{ for } x \in G\}$ , if  $u_0 \leq v_0$ .

**Assumptions.** We make the following assumptions:

- (a)  $\mathcal{L}$  is uniformly elliptic operator in  $\bar{G}$ , i.e., there exists a constant  $\mu > 0$  such that

$$\sum_{j,k=1}^m a_{jk}^i(x) \xi_j \xi_k \geq \mu \sum_{j=1}^m \xi_j^2, \quad i \in S,$$

for all  $\xi = (\xi_1, \dots, \xi_m) \in \mathbb{R}^m$ ,  $x \in G$  and the adjoint operator  $\mathcal{L}^*$  to  $\mathcal{L}$  exists.

- (b) The functions  $a_{jk} = (a_{jk}^i)_{i \in S}$ ,  $b_j = (b_j^i)_{i \in S}$  for  $j, k = 1, \dots, m$  are of class  $C_S^{0+\alpha}(\bar{G})$  and fulfil the Lipschitz condition on  $\partial G$ ; also  $a_{jk}^i(x) = a_{kj}^i(x)$  for every  $i \in S, j, k = 1, \dots, m$  and  $x \in \bar{G}$ .
- (c)  $h \in C_S^{2+\alpha}(\bar{G})$ .
- (d) There exists at least one ordered pair  $u_0, v_0 \in C_S^{2+\alpha}(\bar{G})$  of a lower and an upper function for problem (4), (5) in  $\bar{G}$ , i.e.,

$$u_0(x) \leq v_0(x) \quad \text{for } x \in \bar{G}.$$

- (e)  $f(\cdot, y, z) \in C_S^{0+\alpha}(\bar{G})$  for  $y \in [m_0, M_0], z \in \langle u_0, v_0 \rangle$ .

- (f) For every  $i \in S, x \in \bar{G}, y, \tilde{y} \in \mathcal{B}(S)$  and  $z, \tilde{z} \in C_S(\bar{G})$

$$|f^i(x, y, z) - f^i(x, \tilde{y}, \tilde{z})| \leq L_f (\|y - \tilde{y}\|_{\mathcal{B}(S)} + \|z - \tilde{z}\|_{C_S(\bar{G})}),$$

where  $L_f > 0$  is a constant independent of  $i \in S$ .

- (g)  $f^i$  is an increasing function with respect to the second and third variables for every  $i \in S$ .
- (h)  $u_0(x) \leq h(x) \leq v_0(x)$  for every  $x \in \bar{G}$ .

**Remark.** Let us see that if assumptions (d) and (h) are fulfilled, then the functions  $u_0(x)$  and  $v_0(x)$  are a lower and an upper function for parabolic problem (1), (2), (3) in  $\bar{D}$ .

By applying the monotone iterative method, we may prove the following theorem.

**Theorem 1.** If assumption (a)–(h) hold then problem (1), (2), (3) has the unique solution  $\tilde{u} \in C_S^{0+\alpha}(\bar{D})$  ( $0 < \alpha < 1$ ) within the sector  $\langle u_0, v_0 \rangle$ .

We will outline a proof of the theorem (cf. [5, pp. 49–56, 61–62]). We start from the lower function  $u_0$  and the upper function  $v_0$  and we define by induction two monotone sequences  $\{u_n\}$  and  $\{v_n\}$  as regular solutions of problem (1), (2), (3) with  $u_{n-1}$  and  $v_{n-1}$  substituted for  $u$  in the right-hand sides of the system.

The essential part of the proof is showing that if the functions  $f^i$  fulfil assumptions (e) and (f) and the substituted function  $\beta \in C_S^{0+\alpha}(\bar{D})$  (where  $\beta = u_{n-1}$  and  $\beta = v_{n-1}$ , respectively), then the function  $f^i(x, \beta(t, x), \beta(t, \cdot)) \in C_S^{0+\alpha}(\bar{D})$ .

The function  $\beta \in C_S^{0+\alpha}(\bar{D})$ , so

$$\|\beta(t, x) - \beta(t', x')\|_{\mathcal{B}(S)} \leq H_\beta(|t - t'|^{\frac{\alpha}{2}} + |x - x'|^\alpha),$$

where  $H_\beta > 0$  is some constant. Therefore,

$$\begin{aligned} &|f^i(x, \beta(t, x), \beta(t, \cdot)) - f^i(x', \beta(t', x'), \beta(t', \cdot))| \leq \\ &\quad \leq |f^i(x, \beta(t, x), \beta(t, \cdot)) - f^i(x', \beta(t, x), \beta(t, \cdot))| + \\ &\quad + |f^i(x', \beta(t, x), \beta(t, \cdot)) - f^i(x', \beta(t', x'), \beta(t', \cdot))| \leq \\ &\leq H_f|x - x'|^\alpha + L_f(\|\beta(t, x) - \beta(t', x')\|_{\mathcal{B}(S)} + \|\beta(t, \cdot) - \beta(t', \cdot)\|_{C_S(\bar{G})}) \leq \\ &\leq H_f|x - x'|^\alpha + L_f H_\beta(|t - t'|^{\frac{\alpha}{2}} + |x - x'|^\alpha) + L_f H_\beta|t - t'|^{\frac{\alpha}{2}} \leq \\ &\leq H(|t - t'|^{\frac{\alpha}{2}} + |x - x'|^\alpha), \end{aligned}$$

where  $H = H_f + 2L_f H_\beta$ .

We obtain a solution of problem (1), (2), (3) as the limit of the sequences  $\{u_n\}$  and  $\{v_n\}$ .

For elliptic problem (4), (5), the following existence theorem is known (cf. [9]):

**Theorem 2.** If assumptions (a)–(g) hold, then problem (4), (5) has a solution  $\hat{u} \in C_S(\bar{G}) \cap C_S^2(G)$ .

Let assumptions (a)–(h) hold. We study the behavior of solutions of the parabolic problem with conditions independent of  $t$ .

**Theorem 3.** Let  $v_0(x)$  be an upper function of elliptic problem (4), (5) in  $\bar{G}$  and

$$\begin{cases} \frac{\partial u^i(t, x)}{\partial t} - \mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ u^i(t, x) = v_0^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ u^i(0, x) = v_0^i(x) & \text{for } x \in G, i \in S. \end{cases} \quad (10)$$

Then problem (10) has a solution  $\tilde{v}(t, x) \in C_S^{2+\alpha}(\bar{D})$ , which is nonincreasing with respect to  $t$  and  $\tilde{v}(t, x) \leq v_0(x)$  in  $\bar{D}$ .

*Proof.* By virtue of Theorem 1, parabolic problem (10) has the unique solution  $\tilde{v}(t, x) \in C_S^{2+\alpha}(\bar{D})$ .

The function  $v_0(x)$  is an upper function for elliptic problem (4), (5) and is independent of  $t$ , so  $v_0(x)$  is a solution of the following problem:

$$\begin{cases} \frac{\partial v_0^i(x)}{\partial t} - \mathcal{L}^i[v_0^i](x) \geq f^i(x, v_0(x), v_0(\cdot)) & \text{for } t > 0, x \in G, i \in S, \\ v_0^i(x) = v_0^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ v_0^i(x) = v_0^i(x) & \text{for } x \in G, i \in S. \end{cases} \quad (11)$$

Applying the Szarski theorem on weak partial differential-functional inequalities [8] to problems (10) and (11) we obtain:

$$\tilde{v}(t, x) \leq v_0(x) \text{ in } \bar{D}.$$

Now let

$$\tilde{v}_\tau(t, x) := \tilde{v}(t + \tau, x) \text{ for } \tau > 0.$$

The function  $\tilde{v}_\tau(t, x)$  satisfies the following problem:

$$\begin{cases} \frac{\partial \tilde{v}_\tau^i(t, x)}{\partial t} - \mathcal{L}^i[\tilde{v}_\tau^i](t, x) = f^i(x, \tilde{v}_\tau(t, x), \tilde{v}_\tau(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ \tilde{v}_\tau^i(t, x) = v_0^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ \tilde{v}_\tau^i(0, x) = \tilde{v}^i(\tau, x) \leq v_0^i(x) & \text{for } x \in G, i \in S. \end{cases} \quad (12)$$

Applying again the Szarski theorem on weak partial differential-functional inequalities [8] to problems (10) and (12) we obtain:

$$\tilde{v}_\tau(t, x) \leq \tilde{v}(t, x) \text{ in } \bar{D}.$$

Let  $t_1, t_2 > 0$  and  $t_1 \leq t_2$ ; for  $\tau = t_2 - t_1$  there is

$$\tilde{v}(t_1, x) \geq \tilde{v}_\tau(t_1, x) = \tilde{v}(t_1 + \tau, x) = \tilde{v}(t_2, x) \text{ in } \bar{D},$$

so  $\tilde{v}(t, x)$  is nonincreasing with respect to  $t$ . □

**Theorem 4.** Let  $u_0(x)$  be a lower function for elliptic problem (4), (5) in  $\bar{G}$  and

$$\begin{cases} \frac{\partial u^i(t, x)}{\partial t} - \mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ u^i(t, x) = u_0^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ u^i(0, x) = u_0^i(x) & \text{for } x \in G, i \in S. \end{cases} \quad (13)$$

Then problem (13) has a solution  $\tilde{u}(t, x) \in C_S^{2+\alpha}(\bar{D})$ , which is nondecreasing with respect to  $t$  and  $\tilde{u}(t, x) \geq u_0(x)$  in  $\bar{D}$ .

Now we show the main result of this paper. We prove that the uniform limit at  $t \rightarrow \infty$  of a solution of the parabolic problem is a solution of the elliptic problem.

**Theorem 5.** *If  $u(t, x)$  is a regular uniformly bounded solution of the parabolic boundary initial value problem*

$$\begin{cases} \frac{\partial u^i(t, x)}{\partial t} - \mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ u^i(t, x) = v_0^i(x) & \text{for } t > 0, x \in \partial G, i \in S, \\ u^i(0, x) = v_0^i(x) & \text{for } x \in G, i \in S, \end{cases} \quad (14)$$

and there exists a  $\hat{u}$  such that  $\lim_{t \rightarrow \infty} \|u(t, \cdot) - \hat{u}(\cdot)\|_{C_S(\bar{G})} = 0$ , then the function  $\hat{u}$  is a regular solution of elliptic boundary value problem (4), (5).

*Proof.* First we will prove that  $\hat{u}$  is a weak solution of elliptic problem (4), (5).

Parabolic problem (14) has the unique regular solution by Theorem 1. Multiplying the equations in (14) by a test function  $\xi \in C_0^\infty(G)$  and integrating, we get

$$\left\langle \frac{\partial u^i(t, x)}{\partial t}, \xi(x) \right\rangle - \langle \mathcal{L}^i[u^i](t, x), \xi(x) \rangle = \langle f^i(x, u(t, x), u(t, \cdot)), \xi(x) \rangle$$

for every  $\xi \in C_0^\infty(G)$ ,  $t > 0$ ,  $i \in S$ , and using the adjoint operator  $\mathcal{L}^{*i}$  to  $\mathcal{L}^i$

$$\mathcal{L}^{*i}[g^i](x) := \sum_{j,k=1}^m \frac{\partial^2}{\partial x_j \partial x_k} (a_{jk}^i(x)g^i(x)) - \sum_{j=1}^m \frac{\partial}{\partial x_j} (b_j^i(x)g^i(x))$$

we obtain

$$\left\langle \frac{\partial u^i(t, x)}{\partial t}, \xi(x) \right\rangle - \langle u^i(t, x), \mathcal{L}^{*i}[\xi](x) \rangle = \langle f^i(x, u(t, x), u(t, \cdot)), \xi(x) \rangle$$

for every  $\xi \in C_0^\infty(G)$ ,  $t > 0$ ,  $i \in S$ . Next, we choose any  $T > 0$ , and integrating with respect to  $t$  on the interval  $[0, T]$  and multiplying by  $\frac{1}{T}$  we get

$$\begin{aligned} \frac{1}{T} \int_0^T \left\langle \frac{\partial u^i(t, x)}{\partial t}, \xi(x) \right\rangle dt - \frac{1}{T} \int_0^T \langle u^i(t, x), \mathcal{L}^{*i}[\xi](x) \rangle dt = \\ = \frac{1}{T} \int_0^T \langle f^i(x, u(t, x), u(t, \cdot)), \xi(x) \rangle dt \end{aligned} \quad (15)$$

for every  $\xi \in C_0^\infty(G)$ ,  $i \in S$ . Now, we pass to the limits in (15) as  $T \rightarrow \infty$ . For every  $i \in S$ ,

$$\begin{aligned} \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \left\langle \frac{\partial u^i(t, x)}{\partial t}, \xi(x) \right\rangle dt = \\ = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \frac{\partial}{\partial t} \langle u^i(t, x), \xi(x) \rangle dt = \lim_{T \rightarrow \infty} \frac{1}{T} \langle u^i(T, x), \xi(x) \rangle - \langle u^i(0, x), \xi(x) \rangle = \\ = \lim_{T \rightarrow \infty} \left\langle \frac{u^i(T, x) - u^i(0, x)}{T}, \xi(x) \right\rangle = 0, \end{aligned}$$

because  $\left| \frac{u^i(T,x) - u^i(0,x)}{T} \xi(x) \right| \leq \frac{1}{T} 2C \max_{x \in \bar{G}} |\xi| \rightarrow 0$  as  $T \rightarrow \infty$  and  $G$  is a bounded domain.

Next, for every  $i \in S$

$$\begin{aligned} \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \langle u^i(t,x), \mathcal{L}^{*i}[\xi](x) \rangle dt &= \lim_{T \rightarrow \infty} \left\langle \frac{\int_0^T u^i(t,x) dt}{T}, \mathcal{L}^{*i}[\xi](x) \right\rangle = \\ &= \left\langle \lim_{T \rightarrow \infty} \frac{\int_0^T u^i(t,x) dt}{T}, \mathcal{L}^{*i}[\xi](x) \right\rangle = \left\langle \lim_{T \rightarrow \infty} \frac{\frac{\partial}{\partial t} \int_0^T u^i(t,x) dt}{1}, \mathcal{L}^{*i}[\xi](x) \right\rangle = \\ &= \left\langle \lim_{T \rightarrow \infty} u^i(T,x), \mathcal{L}^{*i}[\xi](x) \right\rangle = \langle \hat{u}^i(x), \mathcal{L}^{*i}[\xi](x) \rangle. \end{aligned}$$

And for every  $i \in S$

$$\begin{aligned} \lim_{T \rightarrow \infty} \left| \frac{1}{T} \int_0^T \langle f^i(x, u(t,x), u(t,\cdot)), \xi(x) \rangle dt - \langle f^i(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \rangle \right| &= \\ &= \left| \left\langle \lim_{T \rightarrow \infty} \frac{\int_0^T f^i(x, u(t,x), u(t,\cdot)) - f^i(x, \hat{u}(x), \hat{u}(\cdot)) dt}{T}, \xi(x) \right\rangle \right| = \\ &= \left| \left\langle \lim_{T \rightarrow \infty} \frac{\frac{\partial}{\partial t} \int_0^T f^i(x, u(t,x), u(t,\cdot)) - f^i(x, \hat{u}(x), \hat{u}(\cdot)) dt}{1}, \xi(x) \right\rangle \right| = \\ &= \left| \left\langle \lim_{T \rightarrow \infty} (f^i(x, u(T,x), u(T,\cdot)) - f^i(x, \hat{u}(x), \hat{u}(\cdot))), \xi(x) \right\rangle \right| \leq \\ &\leq \left\langle \lim_{T \rightarrow \infty} |f^i(x, u(T,x), u(T,\cdot)) - f^i(x, \hat{u}(x), \hat{u}(\cdot))|, |\xi(x)| \right\rangle \leq \\ &\leq \left\langle \lim_{T \rightarrow \infty} (L_1 \|u(T,x) - \hat{u}(x)\|_{\mathcal{B}(S)} + L_2 \|u(T,\cdot) - \hat{u}(\cdot)\|_{C_S(G)}), |\xi(x)| \right\rangle = \\ &= \langle 0, |\xi(x)| \rangle = 0, \end{aligned}$$

so

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \langle f^i(x, u(t,x), u(t,\cdot)), \xi(x) \rangle dt = \langle f^i(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \rangle.$$

Therefore,

$$-\langle \hat{u}^i(x), \mathcal{L}^{*i}[\xi](x) \rangle = \langle f^i(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \rangle$$

and

$$-\langle \mathcal{L}^i[\hat{u}^i](x), \xi(x) \rangle = \langle f^i(x, \hat{u}(x), \hat{u}(\cdot)), \xi(x) \rangle,$$

so  $\hat{u}$  is a weak solution of elliptic problem (4), (5).

Since  $\hat{u}$  is bounded in  $G$ ,  $\hat{u} \in L_S^p(G)$  for any  $p \in [1, \infty]$ . Let  $p > m$ . Thus  $f(x, \hat{u}(x), \hat{u}(\cdot)) \in L_S^p(G)$ .



Now we consider problem

$$\begin{cases} -\mathcal{L}^i[w^i](x) = f^i(x, \hat{u}(x), \hat{u}(\cdot)) & \text{for } x \in G, i \in S, \\ w^i(x) = h^i(x) & \text{for } x \in \partial G, i \in S, \end{cases} \tag{16}$$

System (16) is a system of Dirichlet problems with a single equation each. We apply the Agmon–Douglis–Nirenberg theorem to every problem separately and get  $w = (w^i)_{i \in S} \in H_S^{2,p}(G)$ . By the Agmon–Douglis–Nirenberg theorem, each of the problems included in (16) has the unique solution, so  $\hat{u} = w \in H_S^{2,p}(G)$ .

Because the Sobolev space  $H^{2,p}(\bar{G})$  is continuously imbeddable in  $C^{0+\alpha}(\bar{G})$  for  $p > m$  and then

$$\|u^i\|_{C^{0+\alpha}(\bar{G})} \leq C \|u^i\|_{H^{2,p}(G)}, \quad i \in S,$$

where  $C$  is independent of  $i$  [1, p. 144], we get

$$\hat{u} \in C_S^{0+\alpha}(\bar{G}).$$

Applying the Schauder theorem to (16) for  $\hat{u} \in C_S^{0+\alpha}(\bar{G})$  separately for every  $i \in S$ , we obtain

$$\hat{u} \in C_S^{2+\alpha}(\bar{G}). \quad \square$$

Now using Theorem 5 we show the stability of solutions of the parabolic problem with the conditions independent of time.

**Theorem 6.** *Let assumptions (a)–(h) hold.*

- (i) *If  $\bar{u}$  is a maximal regular solution of problem (4), (5) such that  $h$  fulfils  $\bar{u}(x) \leq h(x)$  for  $x \in \bar{G}$ , then the function  $\bar{u}$  is an asymptotically stable solution from above of parabolic problem (1), (2), (3).*
- (ii) *If  $\underline{u}$  is a minimal regular solution of problem (4), (5) such that  $h$  fulfils  $h(x) \leq \underline{u}(x)$  for  $x \in \bar{G}$ , then the function  $\underline{u}$  is an asymptotically stable solution from below of parabolic problem (1), (2), (3).*
- (iii) *If  $u$  is the unique (i.e.,  $\bar{u} = \underline{u} = u$ ) regular solution of problem (4), (5), then the function  $u$  is an asymptotically stable solution of parabolic problem (1), (2), (3).*

*Proof.* (i) From the theorem on weak partial differential-functional inequalities [8], Theorem 3 and Theorem 5, each solution  $u(t, x)$  of problem (1), (2), (3) such that

$$u_0(x) \leq h(x) \leq v_0(x) \text{ in } \bar{G}$$

satisfies

$$u_0(x) \leq \tilde{u}(t, x) \leq u(t, x) \leq \tilde{v}(t, x) \leq v_0(x) \text{ in } \bar{D},$$

where  $\tilde{u}, \tilde{v}$  are solutions of problems (13) and (10), respectively.

The function  $\bar{u}$  is a maximal regular solution of problem (4), (5); thus the solution  $\tilde{v}(t, x)$  satisfies

$$\bar{u}(x) \leq \tilde{v}(t, x) \leq v_0(x).$$

Hence  $\tilde{v}(t, x)$  is bounded from below and, by Theorem 3, is a nondecreasing function with respect to  $t$ , so  $\lim_{t \rightarrow \infty} \tilde{v}(t, x)$  exists. From Theorem 1 we know that

$$\|\tilde{u}\|_{C_S^{2+\alpha}(\bar{D})} \leq B$$

for  $0 < \alpha < 1$ , where  $B > 0$  is a constant independent of  $i, t, x$ , so  $\{\tilde{u}(t, \cdot)\}_{t \in [0, \infty)}$  are equicontinuous functions.  $\bar{G}$  is a compact set. Thus  $\tilde{v}(t, x)$  converges uniformly as  $t \rightarrow \infty$ . By Theorem 5, this limit is a solution of problem (4), (5).  $\bar{u}(x) \leq \lim_{t \rightarrow \infty} \tilde{v}(t, x)$  and  $\bar{u}(x)$  is a maximal solution of problem (4), (5). Consequently,

$$\lim_{t \rightarrow \infty} \tilde{v}(t, x) = \bar{u}(x).$$

Hence  $u(t, x)$  such that  $\bar{u}(x) \leq u(t, x) \leq \tilde{v}(t, x)$  converges uniformly to  $\bar{u}(x)$ , so  $\bar{u}(x)$  is asymptotically stable solution from above of problem (1), (2), (3).

The proofs of (ii) and (iii) run similarly. □

**Corollary.** *If the function  $h = h(t, x)$  depends on  $t$ , but is bounded by functions  $\check{h}(x), \hat{h}(x) \in C_S^{2+\alpha}(\bar{G})$  independent of  $t$  such that  $u_0(x) \leq \check{h}(x) \leq h(t, x) \leq \hat{h}(x) \leq v_0(x)$  for  $t > 0, x \in \bar{G}$  and an asymptotically stable solution  $u$  of*

$$\begin{cases} \frac{\partial u^i(t, x)}{\partial t} - \mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) & \text{for } t > 0, x \in G, i \in S, \\ u^i(t, x) = h^i(t, x) & \text{for } t > 0, x \in \partial G, i \in S, \\ u^i(0, x) = h^i(0, x) & \text{for } x \in G, i \in S \end{cases}$$

exists, then

$$\check{u}(x) \leq u(x) \leq \hat{u}(x) \quad \text{for } x \in \bar{G},$$

where  $\check{u}$  is the minimal solution of

$$\begin{cases} -\mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) & \text{for } x \in G, i \in S, \\ u^i(t, x) = \check{h}^i(x) & \text{for } x \in \partial G, i \in S, \end{cases}$$

and  $\hat{u}$  is the maximal solution of

$$\begin{cases} -\mathcal{L}^i[u^i](t, x) = f^i(x, u(t, x), u(t, \cdot)) & \text{for } x \in G, i \in S, \\ u^i(t, x) = \hat{h}^i(x) & \text{for } x \in \partial G, i \in S. \end{cases}$$

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