

**AN ALGORITHM
FOR FINDING A COMMON SOLUTION FOR A SYSTEM
OF MIXED EQUILIBRIUM PROBLEM,
QUASI-VARIATIONAL INCLUSION PROBLEM
AND FIXED POINT PROBLEM
OF NONEXPANSIVE SEMIGROUP**

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Abstract. In this paper, we introduce a hybrid iterative scheme for finding a common element of the set of solutions for a system of mixed equilibrium problems, the set of common fixed points for a nonexpansive semigroup and the set of solutions of the quasi-variational inclusion problem with multi-valued maximal monotone mappings and inverse-strongly monotone mappings in a Hilbert space. Under suitable conditions, some strong convergence theorems are proved. Our results extend some recent results in the literature.

Keywords: nonexpansive semigroup, mixed equilibrium problem, viscosity approximation method, quasi-variational inclusion problem, multi-valued maximal monotone mappings, α -inverse-strongly monotone mapping.

Mathematics Subject Classification: 47H09, 47H05.

1. INTRODUCTION

Throughout this paper we assume that H is a real Hilbert space and C is a nonempty closed convex subset of H .

In the sequel, we denote the set of fixed points of a mapping S by $F(S)$.

A bounded linear operator $A : H \rightarrow H$ is said to be *strongly positive*, if there exists a constant $\bar{\gamma}$ such that

$$\langle Ax, x \rangle \geq \bar{\gamma} \|x\|^2, \quad \forall x \in H. \tag{1.1}$$

Let $B : H \rightarrow H$ be a single-valued nonlinear mapping and $M : H \rightarrow 2^H$ be a multi-valued mapping. The “so-called” *quasi-variational inclusion problem* (see, Chang [2, 3]) is to find an $u \in H$ such that

$$\theta \in B(u) + M(u). \tag{1.2}$$

A number of problems arising in structural analysis, mechanics and economics can be studied in a framework of this kind of variational inclusions (see, for example [5]).

The set of solutions of quasi-variational inclusion (1.2) is denoted by $\mathbf{VI}(H, B, M)$.

Special Case

If $M = \partial\delta_C$, where $\partial\delta_C$ is the subdifferential of δ_C , C is a nonempty closed convex subset of H and $\delta_C : H \rightarrow [0, \infty)$ is the indicator function of C , i.e.,

$$\delta_C = \begin{cases} 0, & x \in C, \\ +\infty, & x \notin C, \end{cases}$$

then the quasi-variational inclusion problem (1.2) is equivalent to find $u \in C$ such that

$$\langle B(u), v - u \rangle \geq 0, \quad \forall v \in C. \tag{1.3}$$

This problem is called the *Hartman-Stampacchia variational inequality problem* (see, for example [7]). The set of solutions of (1.3) is denoted by $\mathbf{VI}(C, B)$.

Recall that a mapping $B : H \rightarrow H$ is called α -inverse strongly monotone (see [13]), if there exists an $\alpha > 0$ such that

$$\langle Bx - By, x - y \rangle \geq \alpha \|Bx - By\|^2, \quad \forall x, y \in H.$$

A multi-valued mapping $M : H \rightarrow 2^H$ is called *monotone*, if for all $x, y \in H, u \in Mx$, and $v \in My$, implies that $\langle u - v, x - y \rangle \geq 0$. A multi-valued mapping $M : H \rightarrow 2^H$ is called *maximal monotone*, if it is monotone and if for any $(x, u) \in H \times H$

$$\langle u - v, x - y \rangle \geq 0, \quad \forall (y, v) \in \text{Graph}(M)$$

(the graph of mapping M) implies that $u \in Mx$.

Proposition 1.1 ([13]). *Let $B : H \rightarrow H$ be an α -inverse strongly monotone mapping, then:*

- (a) B is $\frac{1}{\alpha}$ -Lipschitz continuous and a monotone mapping;
- (b) If λ is any constant in $(0, 2\alpha]$, then the mapping $I - \lambda B$ is nonexpansive, where I is the identity mapping on H .

Let C be a nonempty closed convex subset of H , $\Theta : C \times C \rightarrow R$ be an equilibrium bifunction (i.e., $\Theta(x, x) = 0, \forall x \in C$) and let $\varphi : C \rightarrow R$ be a real-valued function.

Recently, Ceng and Yao [1] introduced the following *mixed equilibrium problem* (MEP), i.e., to find $z \in C$ such that

$$MEP : \Theta(z, y) + \varphi(y) - \varphi(z) \geq 0, \quad \forall y \in C. \tag{1.4}$$

The set of solutions of (1.4) is denoted by $MEP(\Theta, \varphi)$, i.e.,

$$MEP(\Theta) = \{z \in C : \Theta(z, y) + \varphi(y) - \varphi(z) \geq 0, \forall y \in C\}.$$

In particular, if $\varphi = 0$, this problem reduces to the *equilibrium problem*, i.e., to find $z \in C$ such that

$$EP : \quad \Theta(z, y) \geq 0, \forall y \in C.$$

Denote the set of solution of EP by $EP(\Theta)$.

On the other hand, Li *et al.* [6] introduced a two step iterative procedure for the approximation of common fixed points of a nonexpansive semigroup $\{T(s) : 0 \leq s < \infty\}$ on a nonempty closed convex subset C in a Hilbert space.

Very recently, Saeidi [9] introduced a more general iterative algorithm for finding a common element of the set of solutions for a system of equilibrium problems and of the set of common fixed points for a finite family of nonexpansive mappings and a nonexpansive semigroup.

Recall that a family of mappings $\mathcal{T} = \{T(s) : 0 \leq s < \infty\} : C \rightarrow C$ is called a *nonexpansive semigroup*, if it satisfies the following conditions:

- (a) $T(s + t) = T(s)T(t)$ for all $s, t \geq 0$ and $T(0) = I$;
- (b) $\|T(s)x - T(s)y\| \leq \|x - y\|, \forall x, y \in C$.
- (c) The mapping $T(\cdot)x$ is continuous, for each $x \in C$.

Motivated and inspired by Ceng and Yao [1], Li *et al.* [6] and Saeidi [9], the purpose of this paper is to introduce a hybrid iterative scheme for finding a common element of the set of solutions for a system of mixed equilibrium problems, the set of common fixed points for a nonexpansive semigroup and the set of solutions of the quasi-variational Inclusion problem with multi-valued maximal monotone mappings and inverse-strongly monotone mappings in Hilbert space. Under suitable conditions, some strong convergence theorems are proved. Our results extends the recent results in Zhang, Lee and Chan [13], Takahashi and Takahashi [11], Chang, Joseph Lee and Chan [4], Ceng and Yao [1], Li *et al.* [6] and Saeidi [9].

2. PRELIMINARIES

In the sequel, we use $x_n \rightharpoonup x$ and $x_n \rightarrow x$ to denote the weak convergence and strong convergence of the sequence $\{x_n\}$ in H , respectively.

Definition 2.1. Let $M : H \rightarrow 2^H$ be a multi-valued maximal monotone mapping, then the single-valued mapping $J_{M,\lambda} : H \rightarrow H$ defined by

$$J_{M,\lambda}(u) = (I + \lambda M)^{-1}(u), \quad \forall u \in H$$

is called the *resolvent operator associated with M* , where λ is any positive number and I is the identity mapping.

Proposition 2.2 ([13]). (a) *The resolvent operator $J_{M,\lambda}$ associated with M is single-valued and nonexpansive for all $\lambda > 0$, i.e.,*

$$\|J_{M,\lambda}(x) - J_{M,\lambda}(y)\| \leq \|x - y\|, \quad \forall x, y \in H, \forall \lambda > 0.$$

(b) *The resolvent operator $J_{M,\lambda}$ is 1-inverse-strongly monotone, i.e.,*

$$\|J_{M,\lambda}(x) - J_{M,\lambda}(y)\|^2 \leq \langle x - y, J_{M,\lambda}(x) - J_{M,\lambda}(y) \rangle, \quad \forall x, y \in H.$$

Definition 2.3. A single-valued mapping $P : H \rightarrow H$ is said to be *hemi-continuous*, if for any $x, y \in H$, the mapping $t \mapsto P(x + ty)$ converges weakly to Px (as $t \rightarrow 0+$).

It is well-known that every continuous mapping must be hemi-continuous.

Lemma 2.4 ([8]). *Let E be a real Banach space, E^* be the dual space of E , $T : E \rightarrow 2^{E^*}$ be a maximal monotone mapping and $P : E \rightarrow E^*$ be a hemi-continuous bounded monotone mapping with $D(P) = E$ then the mapping $S = T + P : E \rightarrow 2^{E^*}$ is a maximal monotone mapping.*

For solving the equilibrium problem for bifunction $\Theta : C \times C \rightarrow R$, let us assume that Θ satisfies the following conditions:

- (H₁) $\Theta(x, x) = 0$ for all $x \in C$.
- (H₂) Θ is monotone, i.e., $\Theta(x, y) + \Theta(y, x) \leq 0$ for all $x, y \in C$.
- (H₃) For each $y \in C$, $x \mapsto \Theta(x, y)$ is concave and upper semicontinuous.
- (H₄) For each $x \in C$, $y \mapsto \Theta(x, y)$ is convex.

A map $\eta : C \times C \rightarrow H$ is called Lipschitz continuous, if there exists a constant $L > 0$ such that

$$\|\eta(x, y)\| \leq L\|x - y\|, \quad \forall x, y \in C.$$

A differentiable function $K : C \rightarrow R$ on a convex set C is called:

(i) η -convex [1] if

$$K(y) - K(x) \geq \langle K'(x), \eta(y, x) \rangle, \quad \forall x, y \in C,$$

where $K'(x)$ is the Fréchet derivative of K at x ;

(ii) η -strongly convex[7] if there exists a constant $\mu > 0$ such that

$$K(y) - K(x) - \langle K'(x), \eta(y, x) \rangle \geq \left(\frac{\mu}{2}\right)\|x - y\|^2, \quad \forall x, y \in C.$$

Let $\Theta : C \times C \rightarrow R$ be an equilibrium bifunction satisfying the conditions (H₁) – (H₄). Let r be any given positive number. For a given point $x \in C$, consider the following *auxiliary problem for MEP* (for short, $MEP(x, r)$): to find $y \in C$ such that

$$\Theta(y, z) + \varphi(z) - \varphi(y) + \frac{1}{r}\langle K'(y) - K'(x), \eta(z, y) \rangle \geq 0, \quad \forall z \in C,$$

where $\eta : C \times C \rightarrow H$ is a mapping and $K'(x)$ is the Fréchet derivative of a functional $K : C \rightarrow R$ at x . Let $V_r^\Theta : C \rightarrow C$ be the mapping such that for each $x \in C$, $V_r^\Theta(x)$ is the solution set of $MEP(x, r)$, i.e.,

$$\begin{aligned} V_r^\Theta(x) = \{y \in C : \Theta(y, z) + \varphi(z) - \varphi(y) + \\ + \frac{1}{r}\langle K'(y) - K'(x), \eta(z, y) \rangle \geq 0, \quad \forall z \in C\}, \quad \forall x \in C. \end{aligned} \tag{2.1}$$

Then the following conclusion holds:

Proposition 2.5 ([1]). *Let C be a nonempty closed convex subset of H , $\varphi : C \rightarrow R$ be a lower semicontinuous and convex functional. Let $\Theta : C \times C \rightarrow R$ be an equilibrium bifunction satisfying conditions (H_1) – (H_4) . Assume that:*

- (i) $\eta : C \times C \rightarrow H$ is Lipschitz continuous with constant $L > 0$ such that:
 - (a) $\eta(x, y) + \eta(y, x) = 0, \forall x, y \in C,$
 - (b) $\eta(\cdot, \cdot)$ is affine in the first variable,
 - (c) for each fixed $y \in C, x \mapsto \eta(y, x)$ is continuous from the weak topology to the weak topology;
- (ii) $K : C \rightarrow R$ is η -strongly convex with constant $\mu > 0$ and its derivative K' is continuous from the weak topology to the strong topology;
- (iii) for each $x \in C,$ there exist a bounded subset $D_x \subseteq C$ and $z_x \in C$ such that for any $y \in C \setminus D_x,$ the following holds:

$$\Theta(y, z_x) + \varphi(z_x) - \varphi(y) + \frac{1}{r} \langle K'(y) - K'(x), \eta(z_x, y) \rangle < 0.$$

Then the following holds:

- (i) V_r^Θ is single-valued;
- (ii) V_r^Θ is nonexpansive if K' is Lipschitz continuous with constant $\nu > 0$ such that $\mu \geq L\nu;$
- (iii) $F(V_r^\Theta) = MEP(\Theta);$
- (iv) $MEP(\Theta)$ is closed and convex.

Lemma 2.6 ([10]). *Let C be a nonempty bounded closed convex subset of H and let $\mathfrak{S} = \{T(s) : 0 \leq s < \infty\}$ be a nonexpansive semigroup on $C,$ then for any $h \geq 0.$*

$$\lim_{t \rightarrow \infty} \sup_{x \in C} \left\| \frac{1}{t} \int_0^t T(s)x ds - T(h) \left(\frac{1}{t} \int_0^t T(s)x ds \right) \right\| = 0.$$

Lemma 2.7 ([6]). *Let C be a nonempty bounded closed convex subset of H and let $\mathfrak{S} = \{T(s) : 0 \leq s < \infty\}$ be a nonexpansive semigroup on $C.$ If $\{x_n\}$ is a sequence in C such that $x_n \rightharpoonup z$ and $\limsup_{s \rightarrow \infty} \limsup_{n \rightarrow \infty} \|T(s)x_n - x_n\| = 0,$ then $z \in F(\mathfrak{S}).$*

3. MAIN RESULTS

In order to prove the main result, we first give the following Lemma.

Lemma 3.1 ([13]). (a) *$u \in H$ is a solution of variational inclusion (1.2) if and only if $u = J_{M,\lambda}(u - \lambda Bu), \forall \lambda > 0,$ i.e.,*

$$VI(H, B, M) = F(J_{M,\lambda}(I - \lambda B)), \forall \lambda > 0.$$

(b) *If $\lambda \in (0, 2\alpha],$ then $VI(H, B, M)$ is a closed convex subset in $H.$*

In the sequel, we assume that $H, C, M, A, B, f, \mathcal{T}, \mathcal{F}, \varphi_i, \eta_i, K_i (i = 1, 2, \dots, N)$ satisfy the following conditions:

- (1) H is a real Hilbert space, $C \subset H$ is a nonempty closed convex subset;
- (2) $A : H \rightarrow H$ is a strongly positive linear bounded operator with coefficient $\bar{\gamma} > 0$, $f : H \rightarrow H$ is a contraction mapping with a contraction constant h ($0 < h < 1$) and $0 < \gamma < \frac{\bar{\gamma}}{h}$, $B : C \rightarrow H$ is a α -inverse-strongly monotone mapping and $M : H \rightarrow 2^H$ is a multi-valued maximal monotone mapping;
- (3) $\mathcal{T} = \{T(s) : 0 \leq s < \infty\} : C \rightarrow C$ is a nonexpansive semigroup;
- (4) $\mathcal{F} = \{\Theta_i : i = 1, 2, \dots, N\} : C \times C \rightarrow R$ is a finite family of bifunctions satisfying conditions $(H_1) - (H_4)$ and $\varphi_i : C \rightarrow R (i = 1, 2, \dots, N)$ is a finite family of lowersemi-continuous and convex functionals;
- (5) $\eta_i : C \times C \rightarrow H$ is a finite family of Lipschitz continuous mappings with constant $L_i > 0 (i = 1, 2, \dots, N)$ such that:
 - (a) $\eta_i(x, y) + \eta_i(y, x) = 0, \forall x, y \in C$,
 - (b) $\eta_i(\cdot, \cdot)$ is affine in the first variable,
 - (c) for each fixed $y \in C, x \mapsto \eta_i(y, x)$ is continuous from the weak topology to the weak topology;
- (6) $K_i : C \rightarrow R$ is a finite family of η_i -strongly convex with constant $\mu_i > 0$ and its derivative K'_i is not only continuous from the weak topology to the strong topology but also Lipschitz continuous with constant $\nu_i > 0, \mu_i \geq L_i \nu_i$.

In the sequel we always denote by $F(\mathcal{T})$ the set of fixed points of the nonexpansive semi-group \mathcal{T} , $VI(H, B, M)$ the set of solutions to the variational inequality (1.2) and $MEP(\mathcal{F})$ the set of solutions to the following *auxiliary problem for a system of mixed equilibrium problems*:

$$\left\{ \begin{array}{l} \Theta_1(y_n^{(1)}, x) + \phi_1(x) - \phi_1(y_n^{(1)}) + \frac{1}{r_1} \langle K'(y_n^{(1)}) - K'(x_n), \eta_1(x, y_n^{(1)}) \rangle \geq 0, \quad \forall x \in C, \\ \Theta_2(y_n^{(2)}, x) + \phi_2(x) - \phi_2(y_n^{(2)}) + \frac{1}{r_2} \langle K'(y_n^{(2)}) - K'(y_n^{(1)}), \eta_2(x, y_n^{(2)}) \rangle \geq 0, \quad \forall x \in C, \\ \vdots \\ \Theta_{N-1}(y_n^{(N-1)}, x) + \phi_{N-1}(x) - \phi_{N-1}(y_n^{(N-1)}) + \\ \quad + \frac{1}{r_{N-1}} \langle K'(y_n^{(N-1)}) - K'(y_n^{(N-2)}), \eta_{N-1}(x, y_n^{(N-1)}) \rangle \geq 0, \quad \forall x \in C, \\ \Theta_N(y_n, x) + \phi_N(x) - \phi_N(y_n) + \\ \quad + \frac{1}{r_N} \langle K'(y_n) - K'(y_n^{(N-1)}), \eta_N(x, y_n) \rangle \geq 0, \quad \forall x \in C, \end{array} \right.$$

where

$$\left\{ \begin{array}{l} y_n^{(1)} = V_{r_1}^{\Theta_1} x_n, \\ y_n^{(i)} = V_{r_i}^{\Theta_i} y_n^{(i-1)} = V_{r_i}^{\Theta_i} V_{r_{(i-1)}}^{\Theta_{i-1}} y_n^{(i-2)} = V_{r_i}^{\Theta_i} \dots V_{r_2}^{\Theta_2} y_n^{(1)} \\ \quad = V_{r_i}^{\Theta_i} \dots V_{r_2}^{\Theta_2} V_{r_1}^{\Theta_1} x_n, \quad i = 2, 3, \dots, N - 1, \\ y_n = V_{r_N}^{\Theta_N} \dots V_{r_2}^{\Theta_2} V_{r_1}^{\Theta_1} x_n, \end{array} \right.$$

and $V_{r_i}^{\Theta_i} : C \rightarrow C, i = 1, 2, \dots, N$ is the mapping defined by (2.1)

In the sequel we denote by $\mathcal{V}^l = V_{r_l}^{\Theta_l} \dots V_{r_2}^{\Theta_2} V_{r_1}^{\Theta_1}$ for $l \in \{1, 2, \dots, N\}$ and $\mathcal{V}^0 = I$.

Theorem 3.2. *Let $H, C, A, B, M, f, \mathcal{T}, \mathcal{F}, \varphi_i, \eta_i, K_i (i = 1, 2, \dots, N)$ be the same as above. Let $\{x_n\}, \{\rho_n\}, \{\xi_n\}$ and $\{y_n\}$ be the explicit iterative sequences generated by $x_1 \in H$ and*

$$\begin{cases} x_{n+1} = \alpha_n \gamma f\left(\frac{1}{t_n} \int_0^{t_n} T(s)x_n ds\right) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A) \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds, \\ \rho_n = J_{M,\lambda}(I - \lambda B)\xi_n, \\ \xi_n = J_{M,\lambda}(I - \lambda B)y_n, \\ y_n = V_{r_N}^{\Theta_N} \dots V_{r_2}^{\Theta_2} V_{r_1}^{\Theta_1} x_n \end{cases} \quad \forall n \geq 1, \tag{3.1}$$

where $r_i (i = 1, 2, \dots, N)$ be a finite family of positive numbers, $\lambda \in (0, 2\alpha], \{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ and $\{t_n\} \subset (0, \infty)$ is a sequence with $t_n \uparrow \infty$. If $\mathcal{G} := F(\mathcal{T}) \cap MEP(\mathcal{F}) \cap VI(H, B, M) \neq \emptyset$ and the following conditions are satisfied:

- (i) for each $x \in C$, there exist a bounded subset $D_x \subseteq C$ and $z_x \in C$ such that for any $y \in C \setminus D_x$,

$$\Theta_i(y, z_x) + \varphi_i(z_x) - \varphi_i(y) + \frac{1}{r_i} \langle K'_i(y) - K'_i(x), \eta_i(z_x, y) \rangle < 0.$$

- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0, \sum_{n=1}^{\infty} \alpha_n = \infty, 0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$, then the sequence $\{x_n\}$ converges strongly to $x^* = P_{\mathcal{G}}(I - A + \gamma f)(x^*)$, provided that $V_{r_i}^{\Theta_i}$ is firmly nonexpansive where $P_{\mathcal{G}}$ is the metric projection of H onto \mathcal{G} .

Proof. We observe that from conditions (ii), we can assume, without loss of generality, that $\alpha_n \leq (1 - \beta_n)\|A\|^{-1}$.

Since A is a linear bounded self-adjoint operator on H , then

$$\|A\| = \sup\{|\langle Au, u \rangle| : u \in H, \|u\| = 1\}.$$

Since

$$\langle ((1 - \beta_n)I - \alpha_n A)u, u \rangle = 1 - \beta_n - \alpha_n \langle Au, u \rangle \geq 1 - \beta_n - \alpha_n \|A\| \geq 0,$$

this implies that $(1 - \beta_n)I - \alpha_n A$ is positive. Hence we have

$$\begin{aligned} \|(1 - \beta_n)I - \alpha_n A\| &= \sup\{|\langle ((1 - \beta_n)I - \alpha_n A)u, u \rangle| : u \in H, \|u\| = 1\} \\ &= \sup\{1 - \beta_n - \alpha_n \langle Au, u \rangle : u \in H, \|u\| = 1\} \leq \\ &\leq 1 - \beta_n - \alpha_n \bar{\gamma} < 1. \end{aligned}$$

Let $Q = P_{\mathcal{G}}$. Note that f is a contraction with coefficient $h \in (0, 1)$. Then, we have

$$\begin{aligned} \|Q(I - A + \gamma f)(x) - Q(I - A + \gamma f)(y)\| &\leq \|(I - A + \gamma f)(x) - (I - A + \gamma f)(y)\| \leq \\ &\leq \|I - A\| \|x - y\| + \gamma \|f(x) - f(y)\| \leq \\ &\leq (1 - \bar{\gamma}) \|x - y\| + \gamma h \|x - y\| = \\ &= (1 - (\bar{\gamma} - \gamma h)) \|x - y\|, \end{aligned}$$

for all $x, y \in H$. Therefore, $Q(I - A + \gamma f)$ is a contraction of H into itself, which implies that there exists a unique element $x^* \in H$ such that $x^* = Q(I - A + \gamma f)(x^*) = P_{\mathcal{G}}(I - A + \gamma f)(x^*)$.

Next, we divide the proof of Theorem 3.2 into 9 steps:

Step 1. First prove the sequences $\{x_n\}$, $\{\rho_n\}$, $\{\xi_n\}$ and $\{y_n\}$ are bounded.

(a) Pick $p \in \mathcal{G}$, since $y_n = \mathcal{V}^N x_n$ and $p = \mathcal{V}^N p$, we have

$$\|y_n - p\| = \|\mathcal{V}^N x_n - p\| \leq \|x_n - p\|. \tag{3.2}$$

(b) Since $p \in VI(H, B, M)$ and $\rho_n = J_{M,\lambda}(I - \lambda B)\xi_n$, we have $p = J_{M,\lambda}(I - \lambda B)p$, and so

$$\begin{aligned} \|\rho_n - p\| &= \|J_{M,\lambda}(I - \lambda B)\xi_n - J_{M,\lambda}(I - \lambda B)p\| \leq \\ &\leq \|(I - \lambda B)\xi_n - (I - \lambda B)p\| \leq \|\xi_n - p\| = \\ &= \|J_{M,\lambda}(I - \lambda B)y_n - J_{M,\lambda}(I - \lambda B)p\| \leq \\ &\leq \|y_n - p\| \leq \|x_n - p\|. \end{aligned} \tag{3.3}$$

Letting $u_n = \frac{1}{t_n} \int_0^{t_n} T(s)x_n ds$, $q_n = \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds$, we have

$$\|u_n - p\| = \left\| \frac{1}{t_n} \int_0^{t_n} T(s)x_n ds - p \right\| \leq \frac{1}{t_n} \int_0^{t_n} \|T(s)x_n - T(s)p\| ds \leq \|x_n - p\|. \tag{3.4}$$

Similarly, we have

$$\|q_n - p\| \leq \|\rho_n - p\|. \tag{3.5}$$

Form (3.1), (3.2), (3.3), (3.4) and (3.5), we have

$$\begin{aligned} \|x_{n+1} - p\| &= \\ &= \|\alpha_n \gamma f(u_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A)q_n - p\| = \\ &= \|\alpha_n \gamma (f(u_n) - f(p)) + \beta_n (x_n - p) + \\ &\quad + ((1 - \beta_n)I - \alpha_n A)(q_n - p) + \alpha_n (\gamma f(p) - Ap)\| \leq \\ &\leq \alpha_n \gamma h \|u_n - p\| + \beta_n \|x_n - p\| + ((1 - \beta_n) - \alpha_n \bar{\gamma}) \|q_n - p\| + \alpha_n \|\gamma f(p) - Ap\| \leq \\ &\leq \alpha_n \gamma h \|x_n - p\| + \beta_n \|x_n - p\| + ((1 - \beta_n) - \alpha_n \bar{\gamma}) \|x_n - p\| + \alpha_n \|\gamma f(p) - Ap\| \leq \\ &\leq (1 - \alpha_n (\bar{\gamma} - \gamma h)) \|x_n - p\| + \alpha_n \|\gamma f(p) - Ap\| \leq \\ &\leq \max \|x_n - p\|, \frac{1}{\bar{\gamma} - \gamma h} \|\gamma f(p) - Ap\| \\ &\vdots \\ &\leq \max \|x_1 - p\|, \frac{1}{\bar{\gamma} - \gamma h} \|\gamma f(p) - Ap\|. \end{aligned}$$

This implies that $\{x_n\}$ is a bounded sequence in H . Therefore $\{y_n\}$, $\{\rho_n\}$, $\{\xi_n\}$, $\{\gamma f(u_n)\}$ and $\{q_n\}$ are all bounded.

Step 2. Next we prove that

$$\|x_{n+1} - x_n\| \rightarrow 0 \quad (n \rightarrow \infty). \tag{3.6}$$

In fact, let us define a sequence $\{z_n\}$ by

$$x_{n+1} = (1 - \beta_n)z_n + \beta_n x_n \quad \forall n \geq 1,$$

then we have

$$\begin{aligned} z_{n+1} - z_n &= \\ &= \frac{x_{n+2} - \beta_{n+1}x_{n+1}}{1 - \beta_{n+1}} - \frac{x_{n+1} - \beta_n x_n}{1 - \beta_n} = \\ &= \frac{\alpha_{n+1}\gamma f(u_{n+1}) + ((1 - \beta_{n+1})I - \alpha_{n+1}A)q_{n+1}}{1 - \beta_{n+1}} - \\ &\quad - \frac{\alpha_n\gamma f(u_n) + ((1 - \beta_n)I - \alpha_n A)q_n}{1 - \beta_n} = \\ &= \frac{\alpha_{n+1}}{1 - \beta_{n+1}}[\gamma f(u_{n+1}) - Aq_{n+1}] - \frac{\alpha_n}{1 - \beta_n}[\gamma f(u_n) - Aq_n] + q_{n+1} - q_n \end{aligned}$$

and so

$$\begin{aligned} &\|z_{n+1} - z_n\| - \|x_{n+1} - x_n\| \leq \\ &\leq \frac{\alpha_{n+1}}{1 - \beta_{n+1}}(\|\gamma f(u_{n+1})\| + \|Aq_{n+1}\|) + \\ &\quad + \frac{\alpha_n}{1 - \beta_n}(\|\gamma f(u_n)\| + \|Aq_n\|) + \left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_{n+1}ds - \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds \right\| + \\ &\quad + \left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\| - \|x_{n+1} - x_n\| \leq \\ &\leq \frac{\alpha_{n+1}}{1 - \beta_{n+1}}(\|\gamma f(u_{n+1})\| + \|Aq_{n+1}\|) + \\ &\quad + \frac{\alpha_n}{1 - \beta_n}(\|\gamma f(u_n)\| + \|Aq_n\|) + \frac{1}{t_{n+1}} \int_0^{t_{n+1}} \|T(s)\rho_{n+1} - T(s)\rho_n\| ds + \\ &\quad + \left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\| - \|x_{n+1} - x_n\|. \end{aligned}$$

$$(3.7)$$

Since $\rho_n = J_{M,\lambda}(I - \lambda B)\xi_n$ and $y_{n+1} = \mathcal{V}^N(x_{n+1})$, $y_n = \mathcal{V}^N(x_n)$, from the nonexpansivity of \mathcal{V}^N , we have

$$\begin{aligned} \|\rho_{n+1} - \rho_n\| &= \|J_{M,\lambda}(I - \lambda B)\xi_{n+1} - J_{M,\lambda}(I - \lambda B)\xi_n\| \leq \\ &\leq \|\xi_{n+1} - \xi_n\| = \\ &= \|J_{M,\lambda}(I - \lambda B)y_{n+1} - J_{M,\lambda}(I - \lambda B)y_n\| \leq \\ &\leq \|y_{n+1} - y_n\| \leq \|x_{n+1} - x_n\|. \end{aligned} \tag{3.8}$$

Substituting (3.8) into (3.7), we get

$$\begin{aligned} \|z_{n+1} - z_n\| - \|x_{n+1} - x_n\| &\leq \\ &\leq \frac{\alpha_{n+1}}{1 - \beta_{n+1}} (\|\gamma f(u_{n+1})\| + \|Aq_{n+1}\|) + \\ &\quad + \frac{\alpha_n}{1 - \beta_n} (\|\gamma f(u_n)\| + \|Aq_n\|) + \frac{1}{t_{n+1}} \int_0^{t_{n+1}} \|T(s)\rho_{n+1} - T(s)\rho_n\| ds + \\ &\quad + \left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\| - \|x_{n+1} - x_n\| \leq \\ &\leq \frac{\alpha_{n+1}}{1 - \beta_{n+1}} (\|\gamma f(u_{n+1})\| + \|Aq_{n+1}\|) + \\ &\quad + \frac{\alpha_n}{1 - \beta_n} (\|\gamma f(u_n)\| + \|Aq_n\|) + \frac{1}{t_{n+1}} \int_0^{t_{n+1}} \|x_{n+1} - x_n\| ds + \\ &\quad + \left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\| - \|x_{n+1} - x_n\| \leq \\ &\leq \frac{\alpha_{n+1}}{1 - \beta_{n+1}} (\|\gamma f(u_{n+1})\| + \|Aq_{n+1}\|) + \frac{\alpha_n}{1 - \beta_n} (\|\gamma f(u_n)\| + \|Aq_n\|) + \\ &\quad + \left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\|. \end{aligned} \tag{3.9}$$

From conditions $t_n \subset (0, \infty)$ and $t_n \uparrow \infty$, we have

$$\begin{aligned} &\left\| \frac{1}{t_{n+1}} \int_0^{t_{n+1}} T(s)\rho_n ds - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\| = \\ &= \left\| \frac{1}{t_{n+1}} \left(\int_0^{t_n} T(s)\rho_n ds + \int_{t_n}^{t_{n+1}} T(s)\rho_n ds \right) - \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds \right\| \leq \\ &\leq \frac{1}{t_n t_{n+1}} \int_0^{t_n} \|(t_n - t_{n+1})T(s)\rho_n\| ds + \frac{1}{t_{n+1}} \int_{t_n}^{t_{n+1}} \|T(s)\rho_n\| ds = \\ &= \frac{t_{n+1} - t_n}{t_{n+1}} M + \frac{t_{n+1} - t_n}{t_{n+1}} M = 2M \left(1 - \frac{t_n}{t_{n+1}}\right) \rightarrow 0, \end{aligned}$$

where $M = \sup_{s \geq 0, n \geq 1} \|T(s)\rho_n\|$. From (3.9) and conditions $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$ that

$$\limsup_{n \rightarrow \infty} (\|z_{n+1} - z_n\| - \|x_{n+1} - x_n\|) \leq 0.$$

Hence, we have

$$\lim_{n \rightarrow \infty} \|z_n - x_n\| = 0.$$

Consequently

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = \lim_{n \rightarrow \infty} (1 - \beta_n)\|z_n - x_n\| = 0.$$

Step 3. Next we prove that

$$\lim_{n \rightarrow \infty} \|x_n - q_n\| = 0. \tag{3.10}$$

Since

$$\begin{aligned} \|x_n - q_n\| &\leq \|x_n - x_{n+1}\| + \|x_{n+1} - q_n\| \leq \\ &\leq \|x_n - x_{n+1}\| + \alpha_n \|\gamma f(u_n) - Aq_n\| + \beta_n \|x_n - q_n\|, \end{aligned}$$

simplifying it we have

$$\|x_n - q_n\| \leq \frac{1}{1 - \beta_n} \|x_n - x_{n+1}\| + \frac{\alpha_n}{1 - \beta_n} \|\gamma f(u_n) - Aq_n\|.$$

Since $\alpha_n \rightarrow 0$, $\|x_{n+1} - x_n\| \rightarrow 0$, and $\{\gamma f(u_n) - Aq_n\}$ is bounded, from the condition $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$, we have $\|x_n - q_n\| \rightarrow 0$.

Step 4. Next we prove that

$$\|x_{n+1} - T(s)x_{n+1}\| \rightarrow 0 \quad (n \rightarrow \infty). \tag{3.11}$$

Since $x_{n+1} = \alpha_n \gamma f(u_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A)q_n$, then

$$\|x_{n+1} - q_n\| \leq \alpha_n \|\gamma f(u_n) - Aq_n\| + \beta_n \|x_n - q_n\|.$$

From condition $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $\|x_n - q_n\| \rightarrow 0$, we have

$$\|x_{n+1} - q_n\| \rightarrow 0. \tag{3.12}$$

Let $K = \{w \in C : \|w - p\| \leq \max\{\|x_1 - p\|, \frac{1}{\bar{\gamma} - \gamma h} \|\gamma f(p) - Ap\|\}$, then K is a nonempty bounded closed convex subset of C and $T(s)$ -invariant. Since $\{x_n\} \subset K$ and K is bounded, there exists $r > 0$ such that $K \subset B_r$, it follows from Lemma 2.6 that

$$\lim_{n \rightarrow \infty} \|q_n - T(s)q_n\| \rightarrow 0. \tag{3.13}$$

From (3.12) and (3.13), we have

$$\begin{aligned} \|x_{n+1} - T(s)x_{n+1}\| &= \|x_{n+1} - q_n + q_n - T(s)q_n + T(s)q_n - T(s)x_{n+1}\| \leq \\ &\leq \|x_{n+1} - q_n\| + \|q_n - T(s)q_n\| + \|T(s)q_n - T(s)x_{n+1}\| \leq \\ &\leq \|x_{n+1} - q_n\| + \|q_n - T(s)q_n\| + \|q_n - x_{n+1}\| \rightarrow 0. \end{aligned}$$

Step 5. Next we prove that

$$\begin{aligned}
 (i) \quad & \lim_{n \rightarrow \infty} \|\mathcal{V}^{l+1}x_n - \mathcal{V}^l x_n\| = 0, \forall l \in \{0, 1, \dots, N - 1\}; \\
 (ii) \quad & \text{Especially, } \lim_{n \rightarrow \infty} \|\mathcal{V}^N x_n - x_n\| = \lim_{n \rightarrow \infty} \|y_n - x_n\| = 0.
 \end{aligned}
 \tag{3.14}$$

In fact, for any given $p \in \mathcal{G}$ and $l \in \{0, 1, \dots, N - 1\}$, Since $V_{r_{l+1}}^{\Theta_{l+1}}$ is firmly nonexpansive, we have

$$\begin{aligned}
 \|\mathcal{V}^{l+1}x_n - p\|^2 &= \|V_{r_{l+1}}^{\Theta_{l+1}}(\mathcal{V}^l x_n) - V_{r_{l+1}}^{\Theta_{l+1}}p\|^2 \leq \\
 &\leq \langle V_{r_{l+1}}^{\Theta_{l+1}}(\mathcal{V}^l x_n) - p, \mathcal{V}^l x_n - p \rangle = \\
 &= \langle \mathcal{V}^{l+1}x_n - p, \mathcal{V}^l x_n - p \rangle = \\
 &= \frac{1}{2}(\|\mathcal{V}^{l+1}x_n - p\|^2 + \|\mathcal{V}^l x_n - p\|^2 - \|\mathcal{V}^l x_n - \mathcal{V}^{l+1}x_n\|^2).
 \end{aligned}$$

It follows that

$$\|\mathcal{V}^{l+1}x_n - p\|^2 \leq \|x_n - p\|^2 - \|\mathcal{V}^l x_n - \mathcal{V}^{l+1}x_n\|^2.
 \tag{3.15}$$

From (3.1), we have

$$\begin{aligned}
 \|x_{n+1} - p\|^2 &= \\
 &= \|\alpha_n \gamma f(u_n) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A)q_n - p\|^2 = \\
 &= \|\alpha_n(\gamma f(u_n) - Ap) + \beta_n(x_n - q_n) + (I - \alpha_n A)(q_n - p)\|^2 \leq \\
 &\leq \|(I - \alpha_n A)(q_n - p) + \beta_n(x_n - q_n)\|^2 + 2\alpha_n \langle \gamma f(u_n) - Ap, x_{n+1} - p \rangle \leq \\
 &\leq [|(I - \alpha_n A)(q_n - p)| + \beta_n \|x_n - q_n\|]^2 + 2\alpha_n \langle \gamma f(u_n) - Ap, x_{n+1} - p \rangle \leq \\
 &\leq [(1 - \alpha_n \bar{\gamma})\|\rho_n - p\| + \beta_n \|x_n - q_n\|]^2 + 2\alpha_n \langle \gamma f(u_n) - Ap, x_{n+1} - p \rangle = \\
 &= (1 - \alpha_n \bar{\gamma})^2 \|\rho_n - p\|^2 + \beta_n^2 \|x_n - q_n\|^2 + 2(1 - \alpha_n \bar{\gamma})\beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + \\
 &\quad + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|.
 \end{aligned}
 \tag{3.16}$$

Since

$$\|\rho_n - p\| \leq \|\xi_n - p\| \leq \|\mathcal{V}^N x_n - p\| \leq \|\mathcal{V}^{l+1}x_n - p\| \forall l \in \{0, 1, \dots, N - 1\}.$$

Substituting (3.15) into (3.16), it yields

$$\begin{aligned}
 \|x_{n+1} - p\|^2 &\leq \\
 &\leq (1 - \alpha_n \bar{\gamma})^2 \{\|x_n - p\|^2 - \|\mathcal{V}^l x_n - \mathcal{V}^{l+1}x_n\|^2\} + \beta_n^2 \|x_n - q_n\|^2 + \\
 &\quad + 2(1 - \alpha_n \bar{\gamma}) \cdot \beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\| = \\
 &= (1 - 2\alpha_n \bar{\gamma} + (\alpha_n \bar{\gamma})^2) \|x_n - p\|^2 - (1 - \alpha_n \bar{\gamma})^2 \|\mathcal{V}^l x_n - \mathcal{V}^{l+1}x_n\|^2 + \beta_n^2 \|x_n - q_n\|^2 + \\
 &\quad + 2(1 - \alpha_n \bar{\gamma})\beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|.
 \end{aligned}$$

Simplifying it we have

$$\begin{aligned} & (1 - \alpha_n \bar{\gamma})^2 \|\mathcal{V}^l x_n - \mathcal{V}^{l+1} x_n\|^2 \leq \\ & \leq \|x_n - p\|^2 - \|x_{n+1} - p\|^2 + \alpha_n \bar{\gamma}^2 \|x_n - p\|^2 + \\ & \quad + \beta_n^2 \|x_n - q_n\|^2 + 2(1 - \alpha_n \bar{\gamma}) \beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + \\ & \quad + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|. \end{aligned}$$

Since $\alpha_n \rightarrow 0$, $\|x_{n+1} - x_n\| \rightarrow 0$, $\|x_n - q_n\| \rightarrow 0$, it yields $\|\mathcal{V}^l x_n - \mathcal{V}^{l+1} x_n\| \rightarrow 0$.

Step 6. Now we prove that for any given $p \in \mathcal{G}$

$$\lim_{n \rightarrow \infty} \|By_n - Bp\| = 0. \tag{3.17}$$

In fact, it follows from (3.3) that

$$\begin{aligned} \|\rho_n - p\|^2 & \leq \|\xi_n - p\|^2 = \|J_{M,\lambda}(I - \lambda B)y_n - J_{M,\lambda}(I - \lambda B)p\|^2 \leq \\ & \leq \|(I - \lambda B)y_n - (I - \lambda B)p\|^2 = \\ & = \|y_n - p\|^2 - 2\lambda \langle y_n - p, By_n - Bp \rangle + \lambda^2 \|By_n - Bp\|^2 \leq \\ & \leq \|y_n - p\|^2 + \lambda(\lambda - 2\alpha) \|By_n - Bp\|^2 \leq \\ & \leq \|x_n - p\|^2 + \lambda(\lambda - 2\alpha) \|By_n - Bp\|^2. \end{aligned} \tag{3.18}$$

Substituting (3.18) into (3.16), we obtain

$$\begin{aligned} \|x_{n+1} - p\|^2 & \leq \\ & \leq (1 - \alpha_n \bar{\gamma})^2 \{ \|x_n - p\|^2 + \lambda(\lambda - 2\alpha) \|By_n - Bp\|^2 \} + \beta_n^2 \|x_n - q_n\|^2 + \\ & \quad + 2(1 - \alpha_n \bar{\gamma}) \beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|. \end{aligned}$$

Simplifying it, we have

$$\begin{aligned} & (1 - \alpha_n \bar{\gamma})^2 \lambda(2\alpha - \lambda) \|By_n - Bp\|^2 \leq \\ & \leq \|x_n - p\|^2 - \|x_{n+1} - p\|^2 + \alpha_n \bar{\gamma}^2 \|x_n - p\|^2 + \beta_n^2 \|x_n - q_n\|^2 + \\ & \quad + 2(1 - \alpha_n \bar{\gamma}) \beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|. \end{aligned}$$

Since $\alpha_n \rightarrow 0$, $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$, $\|x_{n+1} - x_n\| \rightarrow 0$, $\|x_n - q_n\| \rightarrow 0$, and $\{\gamma f(u_n) - Ap\}, \{x_n\}$ are bounded, these imply that $\|By_n - Bp\| \rightarrow 0$ ($n \rightarrow \infty$).

Step 7. Next we prove that

$$\lim_{n \rightarrow \infty} \|y_n - \rho_n\| = 0. \tag{3.19}$$

In fact, since

$$\|y_n - \rho_n\| \leq \|y_n - \xi_n\| + \|\xi_n - \rho_n\|,$$

for the purpose, it is sufficient to prove

$$\|y_n - \xi_n\| \rightarrow 0 \text{ and } \|\xi_n - \rho_n\| \rightarrow 0.$$

(a) First we prove that $\|y_n - \xi_n\| \rightarrow 0$.

In fact, since

$$\begin{aligned} & \|\xi_n - p\|^2 = \\ & = \|J_{M,\lambda}(I - \lambda B)y_n - J_{M,\lambda}(I - \lambda B)p\|^2 \leq \\ & \leq \langle y_n - \lambda By_n - (p - \lambda Bp), \xi_n - p \rangle = \\ & = \frac{1}{2} \{ \|y_n - \lambda By_n - (p - \lambda Bp)\|^2 + \|\xi_n - p\|^2 - \|y_n - \lambda By_n - (p - \lambda Bp) - (\xi_n - p)\|^2 \} \leq \\ & \leq \frac{1}{2} \{ \|y_n - p\|^2 + \|\xi_n - p\|^2 - \|y_n - \xi_n - \lambda(By_n - Bp)\|^2 \} \leq \\ & \leq \frac{1}{2} \{ \|y_n - p\|^2 + \|\xi_n - p\|^2 - \|y_n - \xi_n\|^2 + 2\lambda \langle y_n - \xi_n, By_n - Bp \rangle - \lambda^2 \|By_n - Bp\|^2 \} \end{aligned}$$

we have

$$\|\xi_n - p\|^2 \leq \|y_n - p\|^2 - \|y_n - \xi_n\|^2 + 2\lambda \langle y_n - \xi_n, By_n - Bp \rangle - \lambda^2 \|By_n - Bp\|^2. \tag{3.20}$$

Substituting (3.20) into (3.16), it yields that

$$\begin{aligned} \|x_{n+1} - p\|^2 & \leq (1 - \alpha_n \bar{\gamma})^2 \{ \|y_n - p\|^2 - \|y_n - \xi_n\|^2 + \\ & \quad + 2\lambda \langle y_n - \xi_n, By_n - Bp \rangle - \lambda^2 \|By_n - Bp\|^2 \} + \beta_n^2 \|x_n - q_n\|^2 + \\ & \quad + 2(1 - \alpha_n \bar{\gamma}) \beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|. \end{aligned}$$

Simplifying it we have

$$\begin{aligned} & (1 - \alpha_n \bar{\gamma})^2 \|y_n - \xi_n\|^2 \leq \\ & \leq (\|x_n - x_{n+1}\|) \cdot (\|x_n - p\| + \|x_{n+1} - p\|) + \alpha_n \bar{\gamma}^2 \|x_n - p\|^2 + \\ & \quad + 2(1 - \alpha_n \bar{\gamma}^2) \lambda \langle y_n - \xi_n, By_n - Bp \rangle - (1 - \alpha_n \bar{\gamma})^2 \lambda^2 \|By_n - Bp\|^2 + \beta_n^2 \|x_n - q_n\|^2 + \\ & \quad + 2(1 - \alpha_n \bar{\gamma}) \beta_n \|\rho_n - p\| \cdot \|x_n - q_n\| + 2\alpha_n \|\gamma f(u_n) - Ap\| \cdot \|x_{n+1} - p\|. \end{aligned}$$

Since $\alpha_n \rightarrow 0$, $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$, $\|x_n - q_n\| \rightarrow 0$, $\|By_n - Bp\| \rightarrow 0$ ($n \rightarrow \infty$), $\|x_{n+1} - x_n\| \rightarrow 0$ and $\{\gamma f(u_n) - Ap\}$, $\{x_n\}$, $\{\rho_n\}$ are bounded, these imply that $\|y_n - \xi_n\| \rightarrow 0$ ($n \rightarrow \infty$).

(b) Next we prove that

$$\lim_{n \rightarrow \infty} \|\xi_n - \rho_n\| = 0. \tag{3.21}$$

In fact, since $\|\xi_n - \rho_n\| = \|J_{M,\lambda}(I - \lambda B)y_n - J_{M,\lambda}(I - \lambda B)\xi_n\| \leq \|y_n - \xi_n\| \rightarrow 0$, and so $\|y_n - \rho_n\| = \|y_n - \xi_n + \xi_n - \rho_n\| \leq \|y_n - \xi_n\| + \|\xi_n - \rho_n\| \rightarrow 0$.

Step 8. Next we prove that

$$\limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle \leq 0. \tag{3.22}$$

(a) First, we prove that

$$\limsup_{n \rightarrow \infty} \left\langle \frac{1}{t_n} \int_0^{t_n} T(s) \rho_n ds - x^*, \gamma f(x^*) - Ax^* \right\rangle \leq 0. \tag{3.23}$$

To see this, there exist a subsequence $\{\rho_{n_i}\}$ of $\{\rho_n\}$ such that

$$\begin{aligned} & \limsup_{n \rightarrow \infty} \left\langle \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds - x^*, \gamma f(x^*) - Ax^* \right\rangle = \\ & = \limsup_{i \rightarrow \infty} \left\langle \frac{1}{t_{n_i}} \int_0^{t_{n_i}} T(s)\rho_{n_i} ds - x^*, \gamma f(x^*) - Ax^* \right\rangle \end{aligned}$$

we may also assume that $\rho_{n_i} \rightharpoonup w$, then $q_{n_i} = \frac{1}{t_{n_i}} \int_0^{t_{n_i}} T(s)\rho_{n_i} ds \rightharpoonup w$. Since $\|x_n - q_n\| \rightarrow 0$, we have $x_{n_i} \rightharpoonup w$.

Next, we prove that

$$w \in \mathcal{G}.$$

(1⁰) We first prove that $w \in F(\mathcal{T})$. In fact, since $\{x_{n_i}\} \rightharpoonup w$. From Lemma 2.7 and Step 4, we obtain $w \in F(\mathcal{T})$.

(2⁰) Now we prove that $w \in \cap_{l=1}^N MEP(\Theta_l, \varphi_l)$.

Since $x_{n_i} \rightharpoonup w$ and noting Step 5, without loss of generality, we may assume that $\mathcal{V}^l x_{n_i} \rightharpoonup w, \forall l \in \{0, 1, 2, \dots, N - 1\}$. Hence for any $x \in C$ and for any $l \in \{0, 1, 2, \dots, N - 1\}$, we have

$$\begin{aligned} & \left\langle \frac{K'_{l+1}(\mathcal{V}^{l+1}x_{n_i}) - K'_{l+1}(\mathcal{V}^l x_{n_i})}{r_{l+1}}, \eta_{l+1}(x, \mathcal{V}^{l+1}x_{n_i}) \right\rangle \geq \\ & \geq -\Theta_{l+1}(\mathcal{V}^{l+1}x_{n_i}, x) - \varphi_{l+1}(x) + \varphi_{l+1}(\mathcal{V}^{l+1}x_{n_i}). \end{aligned}$$

By the assumptions and by the condition (H₂) we know that the function φ_i and the mapping $x \mapsto (-\Theta_{l+1}(x, y))$ both are convex and lower semi-continuous, hence they are weakly lower semi-continuous. These together with $\frac{K'_{l+1}(\mathcal{V}^{l+1}x_{n_i}) - K'_{l+1}(\mathcal{V}^l x_{n_i})}{r_{l+1}} \rightarrow 0$ and $\mathcal{V}^{l+1}x_{n_i} \rightharpoonup w$, we have

$$\begin{aligned} 0 & = \liminf_{i \rightarrow \infty} \left\{ \left\langle \frac{K'_{l+1}(\mathcal{V}^{l+1}x_{n_i}) - K'_{l+1}(\mathcal{V}^l x_{n_i})}{r_{l+1}}, \eta_{l+1}(x, \mathcal{V}^{l+1}x_{n_i}) \right\rangle \right\} \geq \\ & \geq \liminf_{i \rightarrow \infty} \{ -\Theta_{l+1}(\mathcal{V}^{l+1}x_{n_i}, x) - \varphi_{l+1}(x) + \varphi_{l+1}(\mathcal{V}^{l+1}x_{n_i}) \}. \end{aligned}$$

i.e.,

$$\Theta_{l+1}(w, x) + \varphi_{l+1}(x) - \varphi_{l+1}(w) \geq 0$$

for all $x \in C$ and $l \in \{0, 1, \dots, N - 1\}$, hence $w \in \cap_{l=1}^N MEP(\Theta_l, \varphi_l)$.

(3⁰) Now we prove that $w \in VI(H, B, M)$.

In fact, since B is α -inverse-strongly monotone, it follows from Proposition 1.1 that B is a $\frac{1}{\alpha}$ -Lipschitz continuous monotone mapping and $D(B) = H$ (where $D(B)$ is the domain of B). It follows from Lemma 2.4 that $M + B$ is maximal monotone. Let $(\nu, g) \in Graph(M + B)$, i.e., $g - B\nu \in M(\nu)$. Since $x_{n_i} \rightharpoonup w$ and noting Step 5, without loss of generality, we may assume that $\mathcal{V}^l x_{n_i} \rightharpoonup w$, in particular, we have

$y_{n_i} = \mathcal{V}^N x_{n_i} \rightarrow w$. From $\|y_n - \rho_n\| \rightarrow 0$, we can prove that $\rho_{n_i} \rightarrow w$. Again since $\rho_{n_i} = J_{M,\lambda}(I - \lambda B)\xi_{n_i}$, we have

$$\xi_{n_i} - \lambda B\xi_{n_i} \in (I + \lambda M)\rho_{n_i}, \text{ i.e., } \frac{1}{\lambda}(\xi_{n_i} - \rho_{n_i} - \lambda B\xi_{n_i}) \in M(\rho_{n_i}).$$

By virtue of the maximal monotonicity of M , we have

$$\langle \nu - \rho_{n_i}, g - B\nu - \frac{1}{\lambda}(\xi_{n_i} - \rho_{n_i} - \lambda B\xi_{n_i}) \rangle \geq 0$$

and so

$$\begin{aligned} \langle \nu - \rho_{n_i}, g \rangle &\geq \langle \nu - \rho_{n_i}, B\nu + \frac{1}{\lambda}(\xi_{n_i} - \rho_{n_i} - \lambda B\xi_{n_i}) \rangle = \\ &= \langle \nu - \rho_{n_i}, B\nu - B\rho_{n_i} + B\rho_{n_i} - B\xi_{n_i} + \frac{1}{\lambda}(\xi_{n_i} - \rho_{n_i}) \rangle \geq \\ &\geq 0 + \langle \nu - \rho_{n_i}, B\rho_{n_i} - B\xi_{n_i} \rangle + \langle \nu - \rho_{n_i}, \frac{1}{\lambda}(\xi_{n_i} - \rho_{n_i}) \rangle. \end{aligned}$$

Since $\|\xi_n - \rho_n\| \rightarrow 0$, $\|B\xi_n - B\rho_n\| \rightarrow 0$ and $\rho_{n_i} \rightarrow w$, we have

$$\lim_{n_i \rightarrow \infty} \langle \nu - \rho_{n_i}, g \rangle = \langle \nu - w, g \rangle \geq 0.$$

Since $M + B$ is maximal monotone, this implies that $\theta \in (M + B)(w)$, i.e., $w \in VI(H, B, M)$, and so $w \in \mathcal{G}$.

Since $x^* = P_{\mathcal{G}}(I - A + \gamma f)(x^*)$, we have

$$\begin{aligned} \limsup_{n \rightarrow \infty} \langle \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds - x^*, \gamma f(x^*) - Ax^* \rangle &= \\ &= \limsup_{i \rightarrow \infty} \langle \frac{1}{t_{n_i}} \int_0^{t_{n_i}} T(s)\rho_{n_i} ds - x^*, \gamma f(x^*) - Ax^* \rangle = \\ &= \limsup_{i \rightarrow \infty} \langle q_{n_i} - x^*, \gamma f(x^*) - Ax^* \rangle = \\ &= \langle w - x^*, \gamma f(x^*) - Ax^* \rangle \leq 0. \end{aligned}$$

(b) Now we prove that

$$\limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle \leq 0.$$

From $\|x_{n+1} - q_n\| \rightarrow 0$ and (a), we have

$$\begin{aligned} \limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle &= \\ &= \limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - Ax^*, x_{n+1} - q_n + q_n - x^* \rangle \leq \\ &\leq \limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - Ax^*, x_{n+1} - q_n \rangle + \limsup_{n \rightarrow \infty} \langle \gamma f(x^*) - Ax^*, q_n - x^* \rangle \leq 0. \end{aligned}$$

Step 9. Finally we prove that

$$x_n \rightarrow x^*.$$

Indeed, from (3.1) , we have

$$\begin{aligned} & \|x_{n+1} - x^*\|^2 = \\ & = \|\alpha_n(\gamma f(u_n) - Ax^*) + \beta_n(x_n - x^*) + ((1 - \beta_n)I - \alpha_n A)(q_n - x^*)\|^2 \leq \\ & \leq \|\beta_n(x_n - x^*) + ((1 - \beta_n)I - \alpha_n A)(q_n - x^*)\|^2 + 2\alpha_n \langle \gamma f(u_n) - Ax^*, x_{n+1} - x^* \rangle \leq \\ & \leq [\|((1 - \beta_n)I - \alpha_n A)(q_n - x^*)\| + \beta_n \|x_n - x^*\|]^2 + \\ & \quad + 2\alpha_n \gamma \langle f(u_n) - f(x^*), x_{n+1} - x^* \rangle + 2\alpha_n \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle \leq \\ & \leq [\|(1 - \beta_n - \alpha_n \bar{\gamma})\| \rho_n - x^*\| + \beta_n \|x_n - x^*\|]^2 + 2\alpha_n \gamma h \|x_n - x^*\| \cdot \|x_{n+1} - x^*\| + \\ & \quad + 2\alpha_n \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle \leq \\ & \leq (1 - \alpha_n \bar{\gamma})^2 \|x_n - x^*\|^2 + \alpha_n \gamma h \{ \|x_n - x^*\|^2 + \|x_{n+1} - x^*\|^2 \} + \\ & \quad + 2\alpha_n \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle. \end{aligned}$$

This implies that

$$\begin{aligned} & \|x_{n+1} - x^*\|^2 \leq \\ & \leq \frac{(1 - \alpha_n \bar{\gamma})^2 + \alpha_n \gamma h}{1 - \alpha_n \gamma h} \|x_n - x^*\|^2 + \frac{2\alpha_n}{1 - \alpha_n \gamma h} \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle = \\ & = [1 - \frac{2(\bar{\gamma} - \gamma h)\alpha_n}{1 - \alpha_n \gamma h}] \|x_n - x^*\|^2 + \frac{(\alpha_n \bar{\gamma})^2}{1 - \alpha_n \gamma h} \|x_n - x^*\|^2 + \frac{2\alpha_n}{1 - \alpha_n \gamma h} \langle \gamma f(x^*) - \\ & \quad - Ax^*, x_{n+1} - x^* \rangle \leq \\ & \leq [1 - \frac{2(\bar{\gamma} - \gamma h)\alpha_n}{1 - \alpha_n \gamma h}] \|x_n - x^*\|^2 + \frac{2(\bar{\gamma} - \gamma h)\alpha_n}{1 - \alpha_n \gamma h} \{ \frac{\alpha_n \bar{\gamma}^2}{2(\bar{\gamma} - \gamma h)} \|x_n - x^*\|^2 + \\ & \quad + \frac{1}{\bar{\gamma} - \gamma h} \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle \} = \\ & = (1 - l_n) \|x_n - x^*\|^2 + \delta_n, \end{aligned}$$

where

$$l_n = \frac{2(\bar{\gamma} - \gamma h)\alpha_n}{1 - \alpha_n \gamma h},$$

and

$$\delta_n = \frac{2(\bar{\gamma} - \gamma h)\alpha_n}{1 - \alpha_n \gamma h} \{ \frac{\alpha_n \bar{\gamma}^2}{2(\bar{\gamma} - \gamma h)} \|x_n - x^*\|^2 + \frac{1}{\bar{\gamma} - \gamma h} \langle \gamma f(x^*) - Ax^*, x_{n+1} - x^* \rangle \}.$$

It is easy to see that $l_n \rightarrow 0$, $\sum_{n=1}^\infty l_n = \infty$ and $\limsup_{n \rightarrow \infty} \frac{\delta_n}{l_n} \leq 0$. Hence the sequence $\{x_n\}$ converges strongly to x^* .

This completes the proof of Theorem 3.2. □

Corollary 3.3. *Let $H, C, A, B, M, f, \mathcal{T}, \mathcal{F}, \varphi_i, \eta_i, K_i (i = 1, 2, \dots, N)$ be the same as Theorem 3.2. Let $\{x_n\}, \{\rho_n\}, \{\xi_n\}$ and $\{y_n\}$ be explicit iterative sequences generated by $x_1 \in H$ and*

$$\begin{cases} x_{n+1} = \alpha_n \gamma f\left(\frac{1}{t_n} \int_0^{t_n} T(s)x_n ds\right) + \beta_n x_n + ((1 - \beta_n)I - \alpha_n A) \frac{1}{t_n} \int_0^{t_n} T(s)\rho_n ds, \\ \rho_n = P_C(I - \lambda B)\xi_n, \\ \xi_n = P_C(I - \lambda B)y_n, \\ y_n = V_{r_N}^{\Theta_N} \dots V_{r_2}^{\Theta_2} V_{r_1}^{\Theta_1} x_n, \end{cases} \quad \forall n \geq 1, \tag{3.24}$$

where $r_i (i = 1, 2, \dots, N)$ are a finite family of positive numbers, $\lambda \in (0, 2\alpha]$, $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ and $\{t_n\} \subset (0, \infty)$ is a sequence with $t_n \uparrow \infty$. If $\mathcal{G} := F(\mathcal{T}) \cap MEP(\mathcal{F}) \cap VI(C, B) \neq \emptyset$ and the following conditions are satisfied:

- (i) for each $x \in C$, there exist a bounded subset $D_x \subseteq C$ and $z_x \in C$ such that for any $y \in C \setminus D_x$,

$$\Theta_i(y, z_x) + \varphi_i(z_x) - \varphi_i(y) + \frac{1}{r_i} \langle K'_i(y) - K'_i(x), \eta_i(z_x, y) \rangle < 0,$$

- (ii) $\lim_{n \rightarrow \infty} \alpha_n = 0, \sum_{n=1}^{\infty} \alpha_n = \infty, 0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1,$

then the sequence $\{x_n\}$ converges strongly to some point $x^* = P_{\mathcal{G}}(I - A + \gamma f)(x^*)$, provided that $V_{r_i}^{\Theta_i}$ is firmly nonexpansive.

Proof. Taking $M = \partial\delta_C : H \rightarrow 2^H$ in Theorem 3.2, where $\delta_C : H \rightarrow [0, \infty)$ is the indicator function of C , i.e.,

$$\delta_C = \begin{cases} 0, & x \in C, \\ +\infty, & x \notin C, \end{cases}$$

then the variational inclusion problem (1.2) is equivalent to variational inequality (1.3), i.e., to find $u \in C$ such that

$$\langle B(u), v - u \rangle \geq 0, \forall v \in C.$$

Again, since $M = \partial\delta_C$, the restriction of $J_{M,\lambda}$ on C is an identity mapping, i.e., $J_{M,\lambda}|_C = I$ and so we have

$$P_C(I - \lambda B)k_n = J_{M,\lambda}(P_C(I - \lambda B)k_n); \quad P_C(I - \lambda B)y_n = J_{M,\lambda}(P_C(I - \lambda B)y_n).$$

Hence the conclusion of Corollary 3.3 can be obtained from Theorem 3.2 immediately. □

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